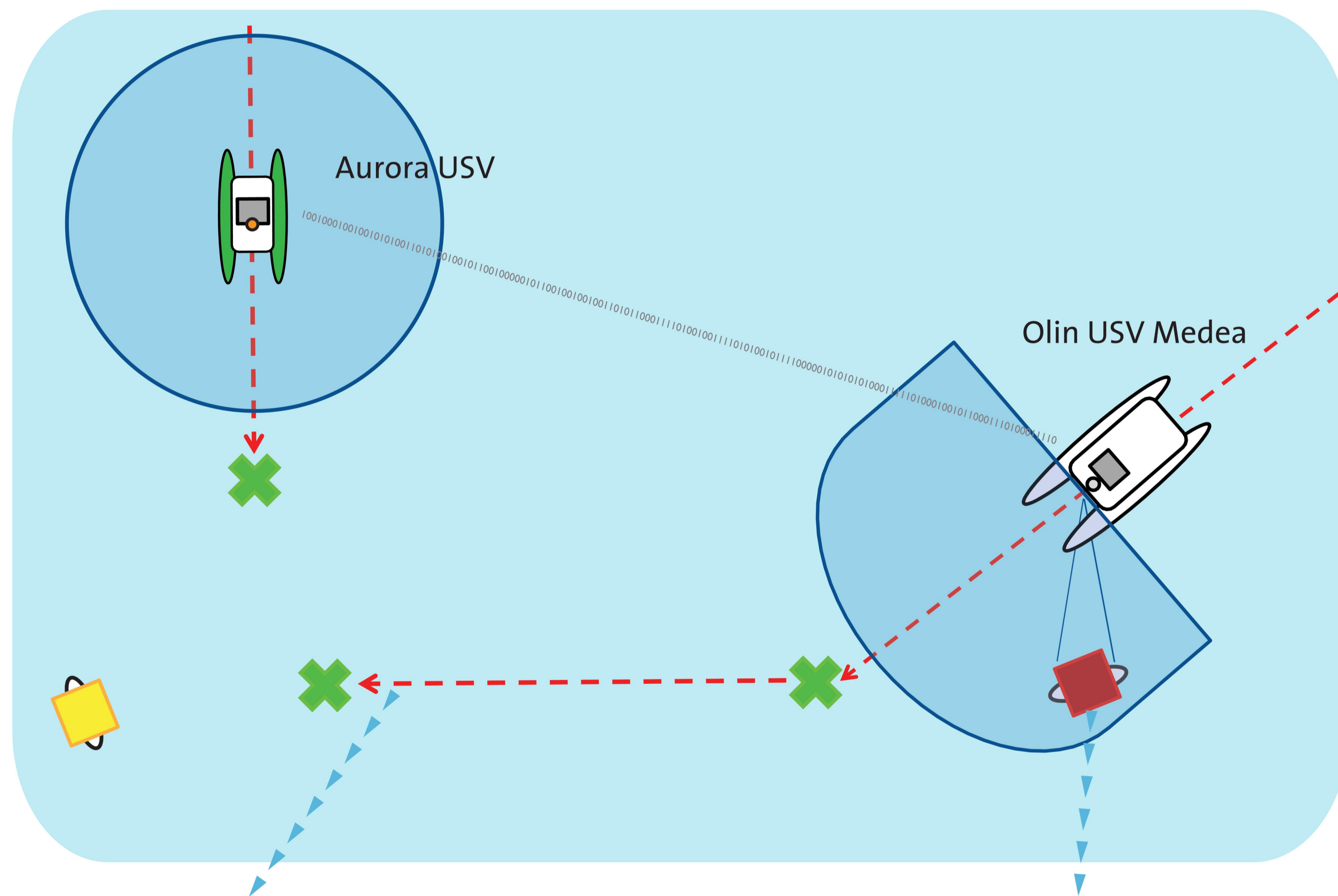


Autonomous Unmanned Surface Vehicle

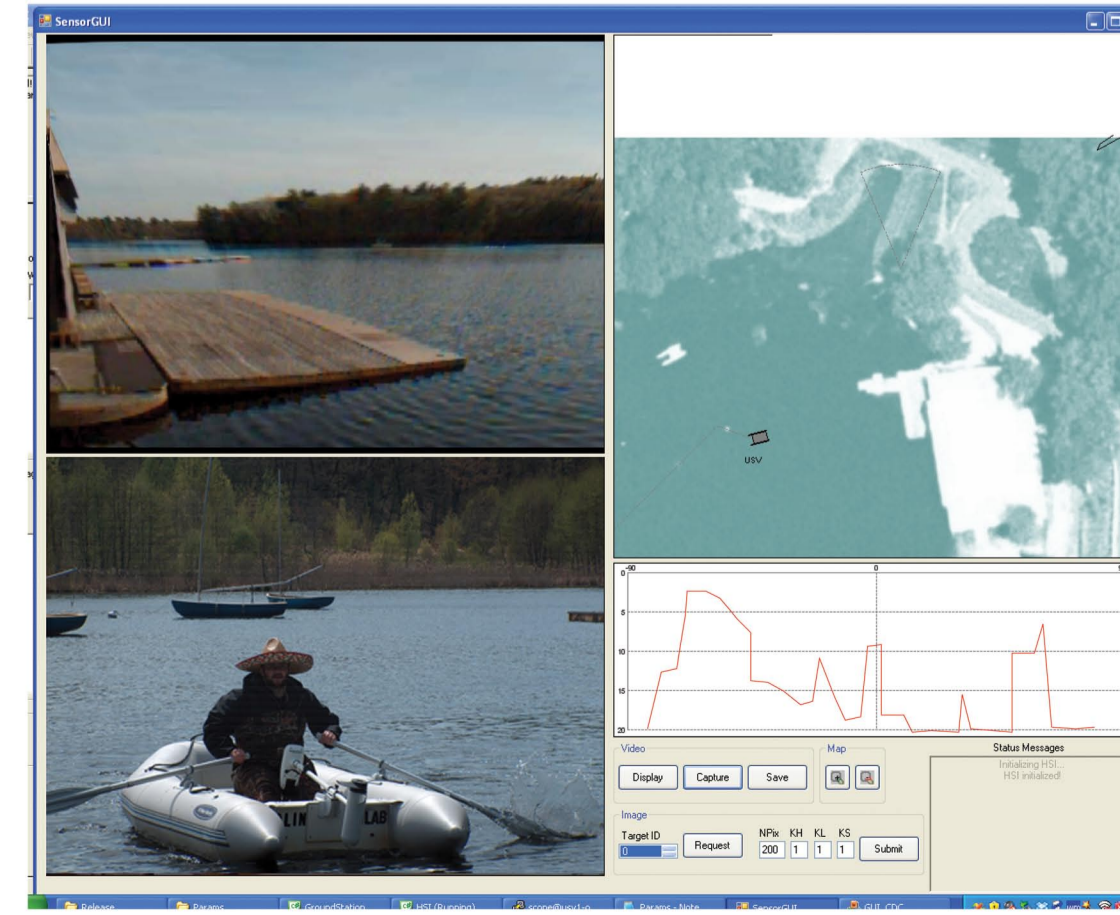
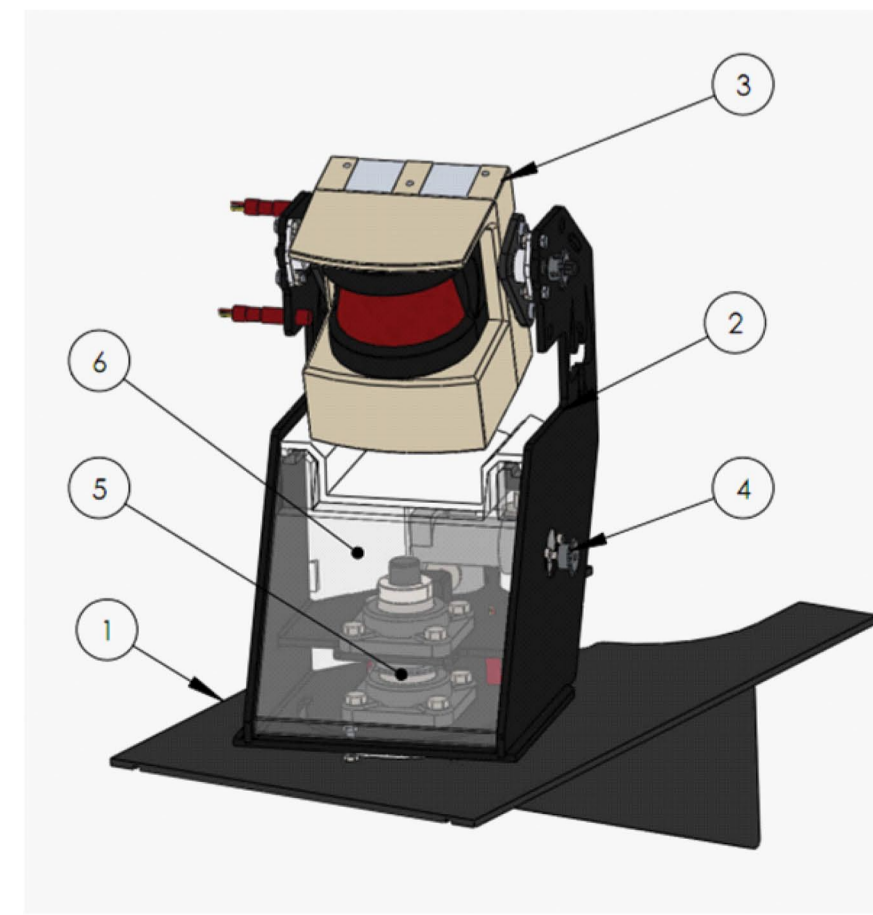
Mission: To build and demonstrate an autonomous unmanned surface vehicle (USV) that uses Aurora Flight Sciences' On-board Planning Module multi-vehicle coordination software to jointly perform a mission with another USV.

The Demo

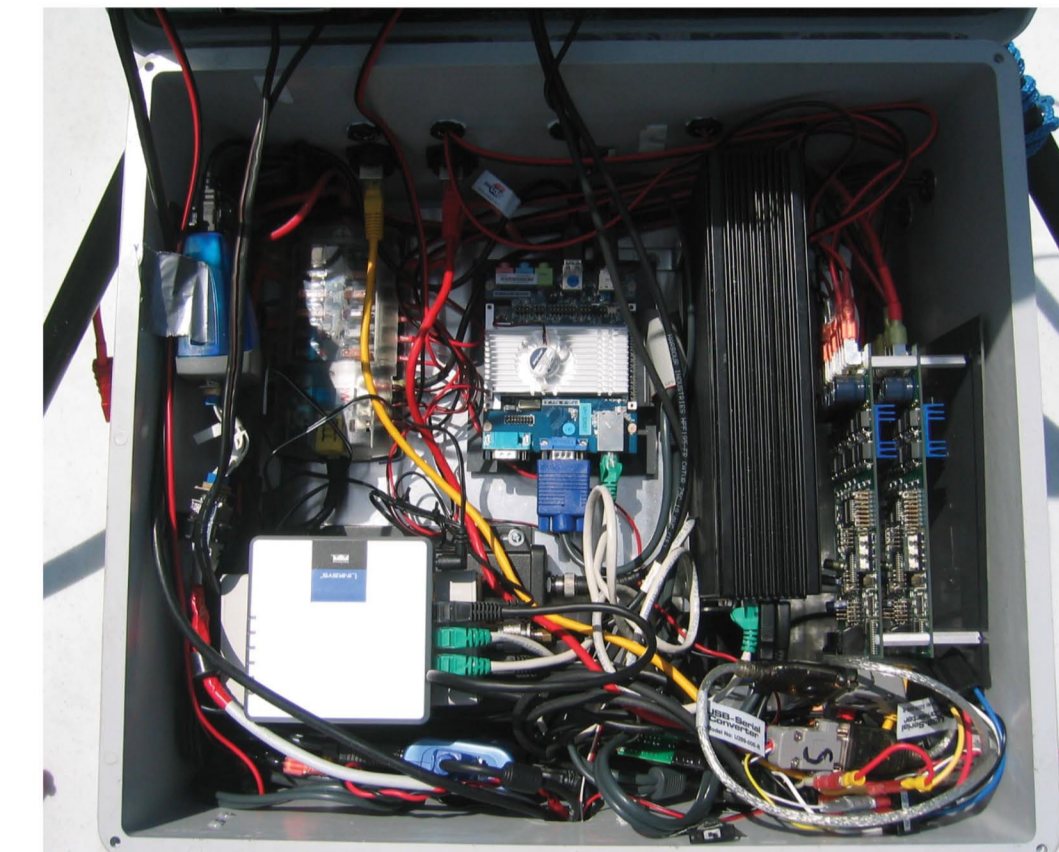
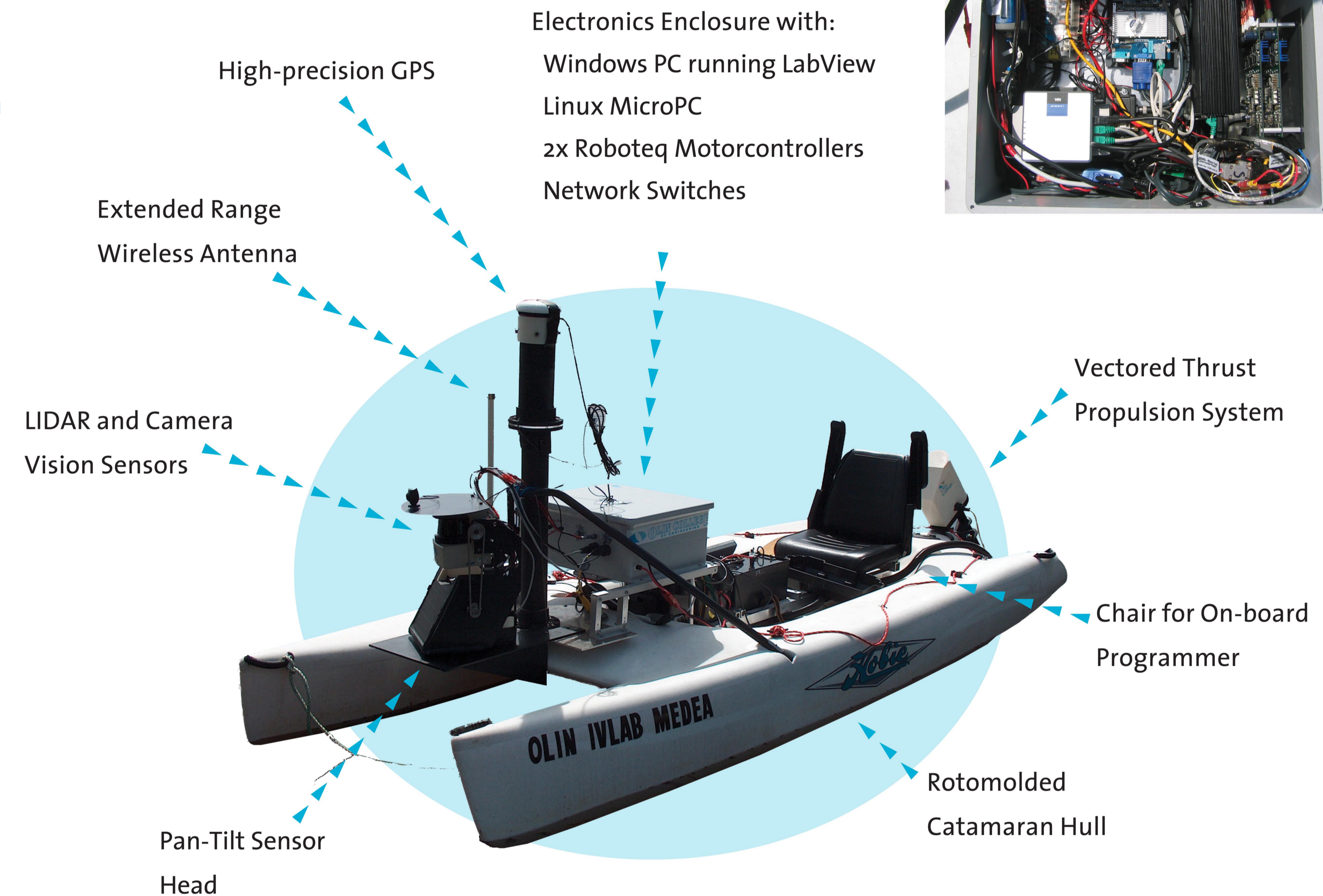


Waypoint Following

Sensing & Target Tracking



USV Medea



Project Team

- Andrea Striz - Project Manager
- Joe Holler - Captain and Mechanical Lead
- Joe Kendall - Safety & Operations Officer
- John Morgan - Navigation Officer
- Nik Wittenstein - Test Pilot and Controls Officer
- Tony Lopez - Communications Officer

Special Thanks to our many wonderful advisors:

Dave Barrett - Olin, Tony Abad - Aurora, Olivier Toupet - Aurora, Andre Devitt - Aurora

